

N-body simulations

Phys 750 Lecture 10

N-body simulations

- ▶ Forward integration in time of strongly coupled classical particles or (rigid-body composite objects)

- ▶ Very general class of second-order ODE:

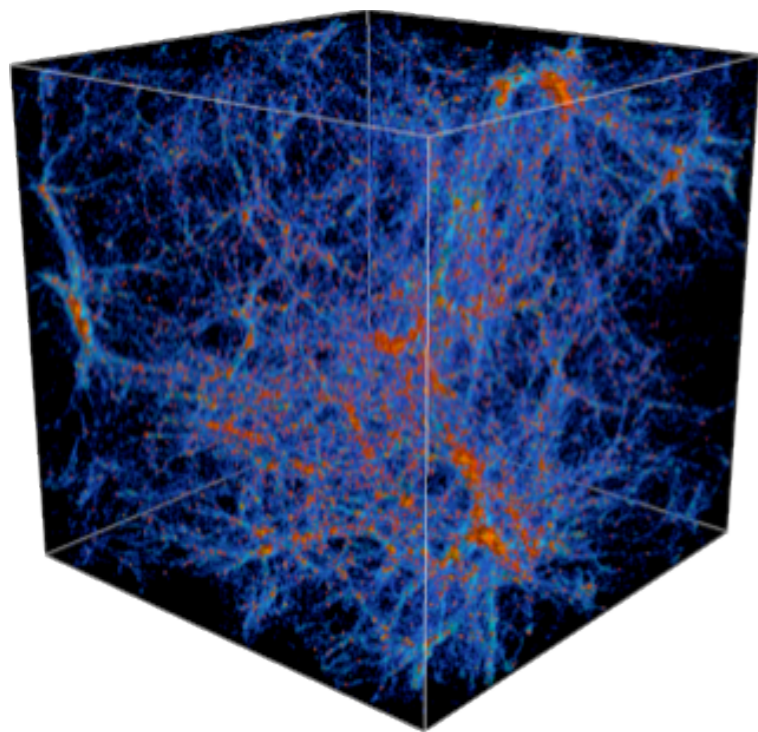
$$m_i \ddot{\mathbf{r}}_i = \underbrace{\xi_i}_{\text{Brownian motion}} - \underbrace{\gamma_i \dot{\mathbf{r}}_i - \tilde{\gamma} |\dot{\mathbf{r}}_i| \dot{\mathbf{r}}_i - \dots}_{\text{dissipation}} + \underbrace{\sum_{j \neq i} F^{(2)}(\mathbf{r}_i, \mathbf{r}_j) + \sum_{\substack{j < k \\ j, k \neq i}} F^{(3)}(\mathbf{r}_i, \mathbf{r}_j, \mathbf{r}_k) + \dots}_{\text{arbitrary forces}}$$

- ▶ Referred to as **N-body simulation** or **molecular dynamics** in various scientific communities

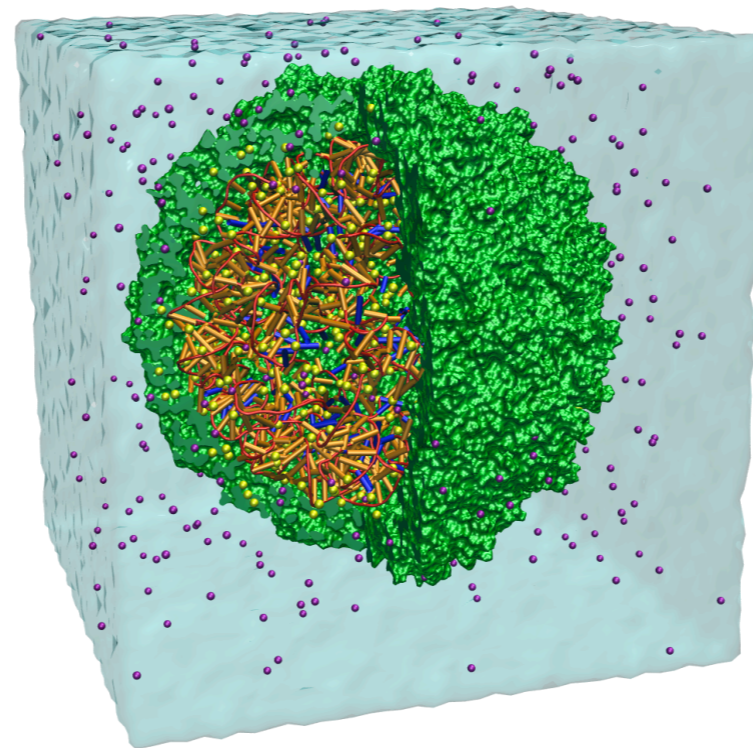
Broad applicability

- ▶ Useful in many contexts and over vastly different scales

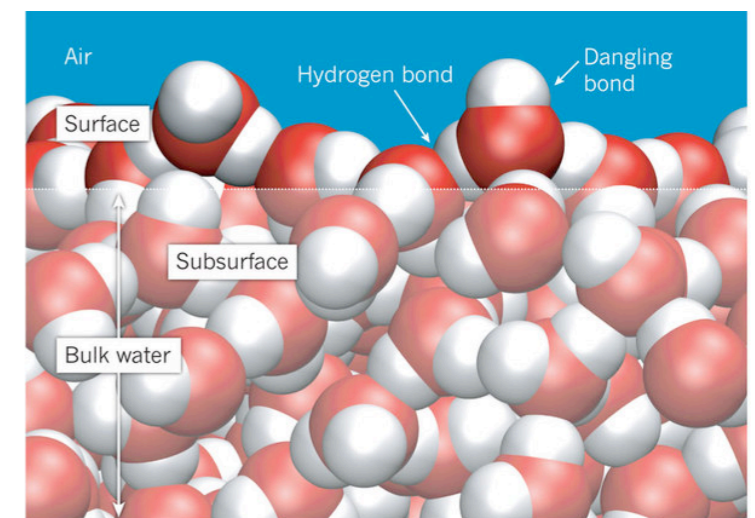
galaxy formation



virus



"classical water"



N-body simulations

- ▶ Classical systems of many particles, dissipationless and interacting via central forces, have a Hamiltonian of the form

$$H = \sum_i \frac{p_i^2}{2m_i} + \sum_{i<j} U(r_{ij})$$

- ▶ Momentum variables $\mathbf{p}_i = m_i \mathbf{v}_i$ are conjugate to the position variables \mathbf{r}_i ($2DN$ -dimensional phase space)
- ▶ Interactions determined by the pair potential $U(r)$

N-body simulations

- ▶ The set of second-order differential equations maps to a set of coupled first-order equations:

$$\dot{\mathbf{r}}_i = \frac{\partial H}{\partial \mathbf{p}_i} = \frac{\mathbf{p}_i}{m_i} = \mathbf{v}_i$$
$$\dot{\mathbf{p}}_i = -\frac{\partial H}{\partial \mathbf{r}_i} = -\sum_{j \neq i} \frac{\partial U(r_{ij})}{\partial \mathbf{r}_i} = -\sum_{j \neq i} U'(r_{ij}) \hat{\mathbf{r}}_{ij}$$

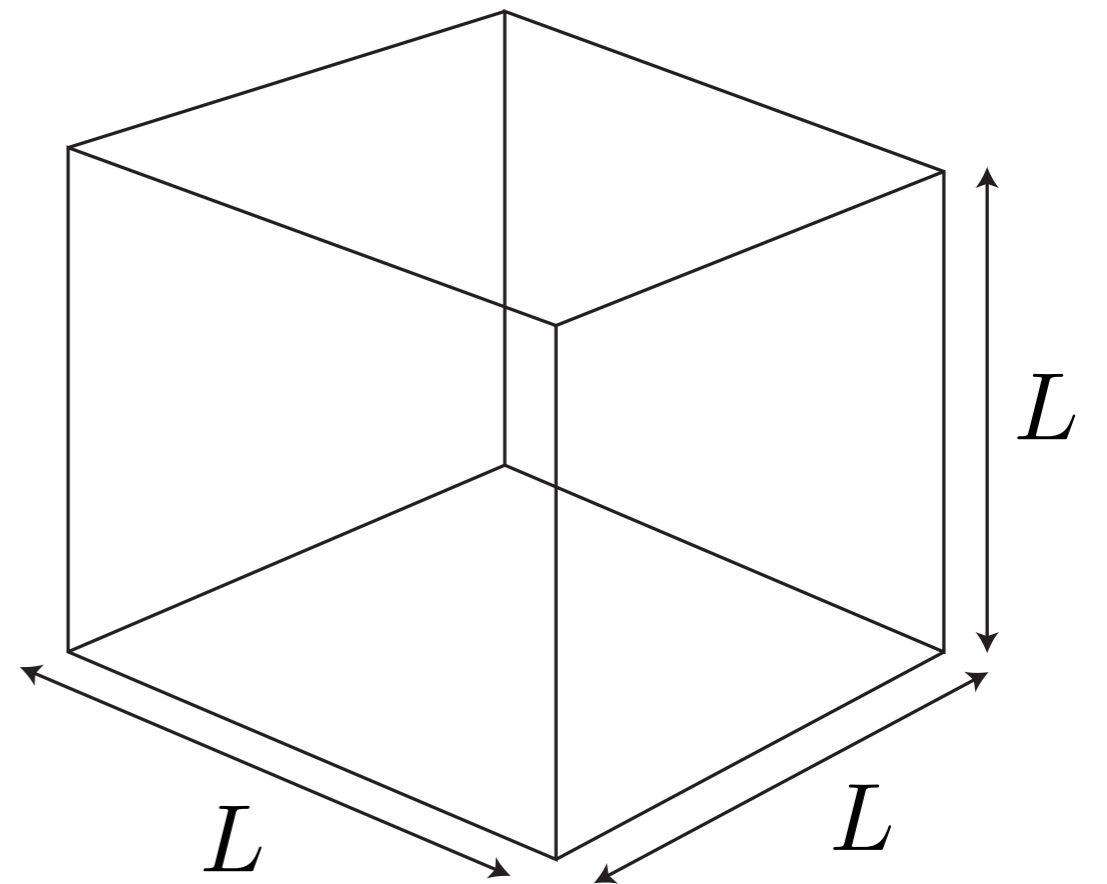
net force exerted by the
other $N - 1$ particles

N-body simulations

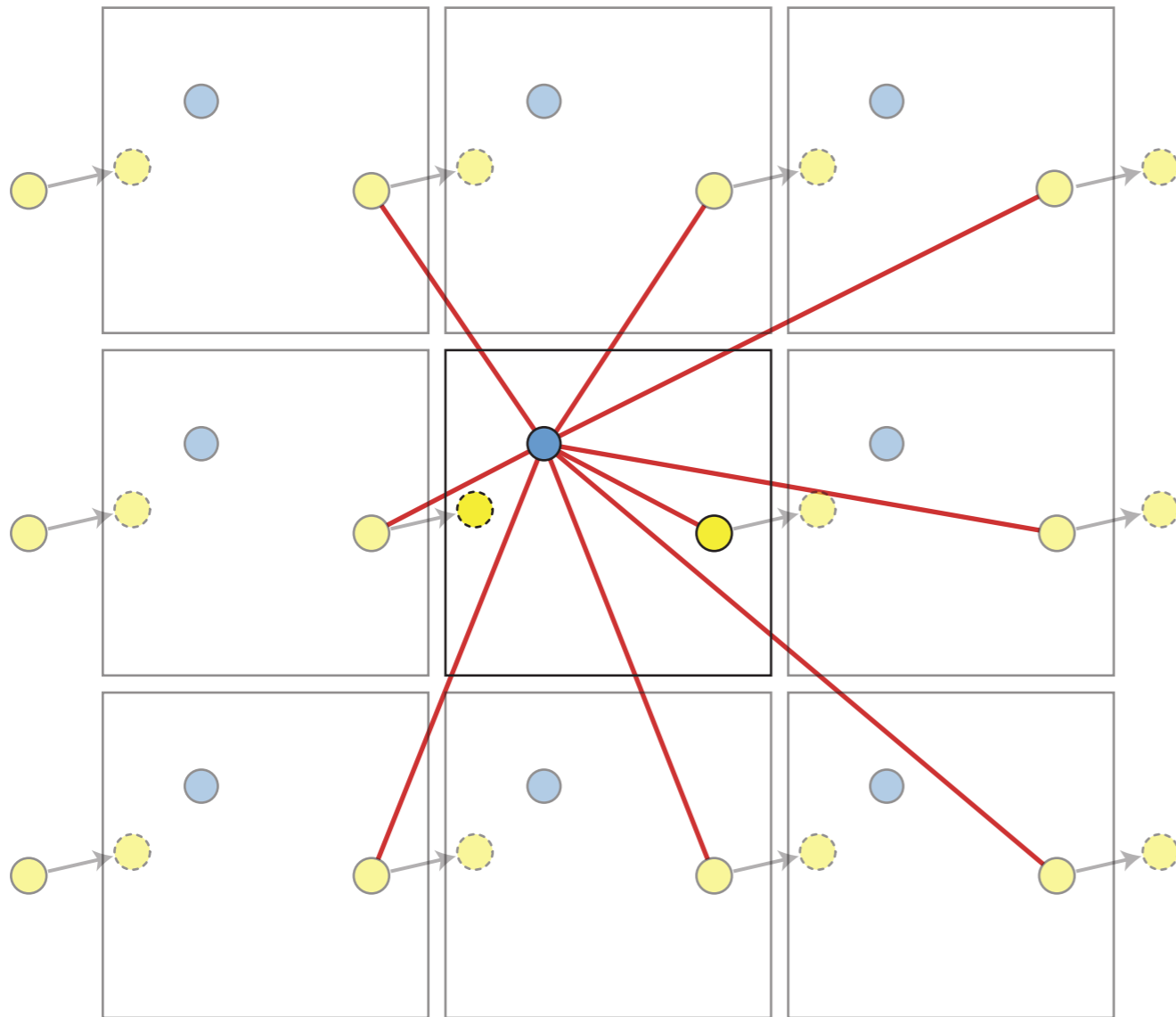
- ▶ Special considerations:
 - ▶ For long-range forces all particle pairs interact strongly with one another – at best, $N(N - 1)/2$ scaling
 - ▶ Repulsive interactions require a “container” (via walls or periodic boundary conditions)
 - ▶ Time step must be adjusted such that the length scale $v\Delta t$ can resolve the spatial structure of $U(r)$

Finite simulation cell

- ▶ Typical setup: finite $L \times L \times L$ periodic cell serves as a representative sample of space
- ▶ How to judge **distance** for the purpose of computing long range forces?



Finite simulation cell



- ▶ Periodicity is equivalent to tiling all space with copies of the same cell
- ▶ Forces arise from interactions with each of an infinite number of image particles

Finite simulation cell

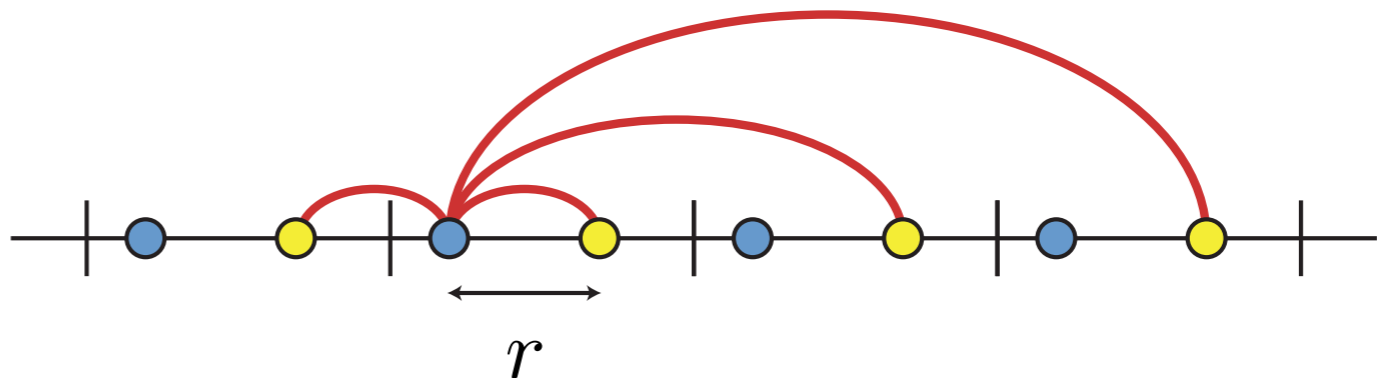
- ▶ Approximating the infinite summation in 1D:

$$F^{\text{eff}}(r) = \sum_{n=-\infty}^{\infty} F(r + nL) = \dots + F(r - L) + F(r) + F(r + L) + \dots$$

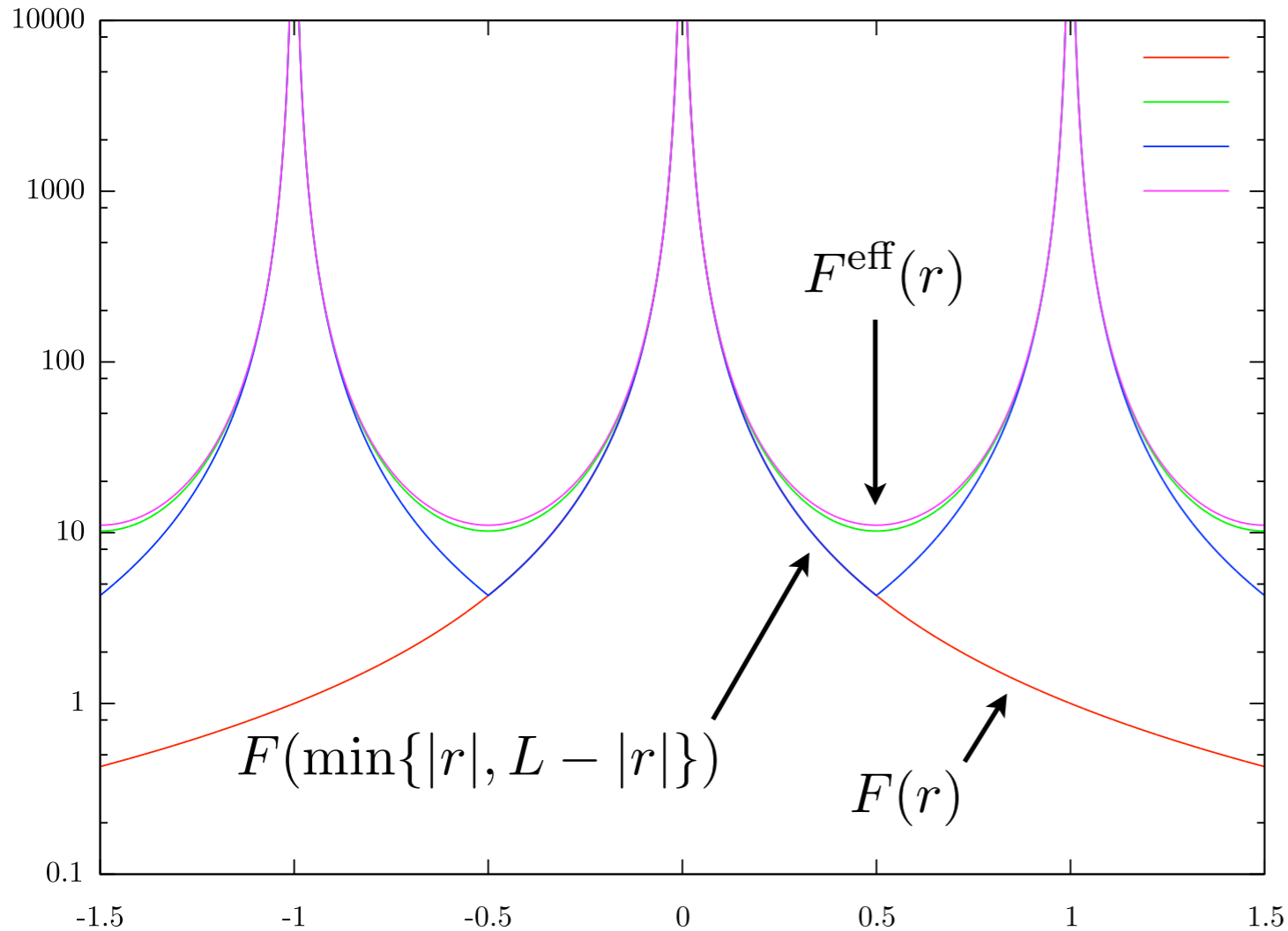
$$\approx F(\min\{|r|, L - |r|\}) \quad \text{closest-image distance}$$

intra-cell separation

$$-L < r < L$$



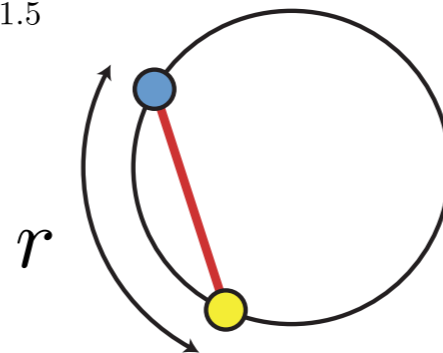
Finite simulation cell



- Summation has an exact form for EM-like and gravity-like interactions

$$F(r) = \frac{1}{r^2}$$

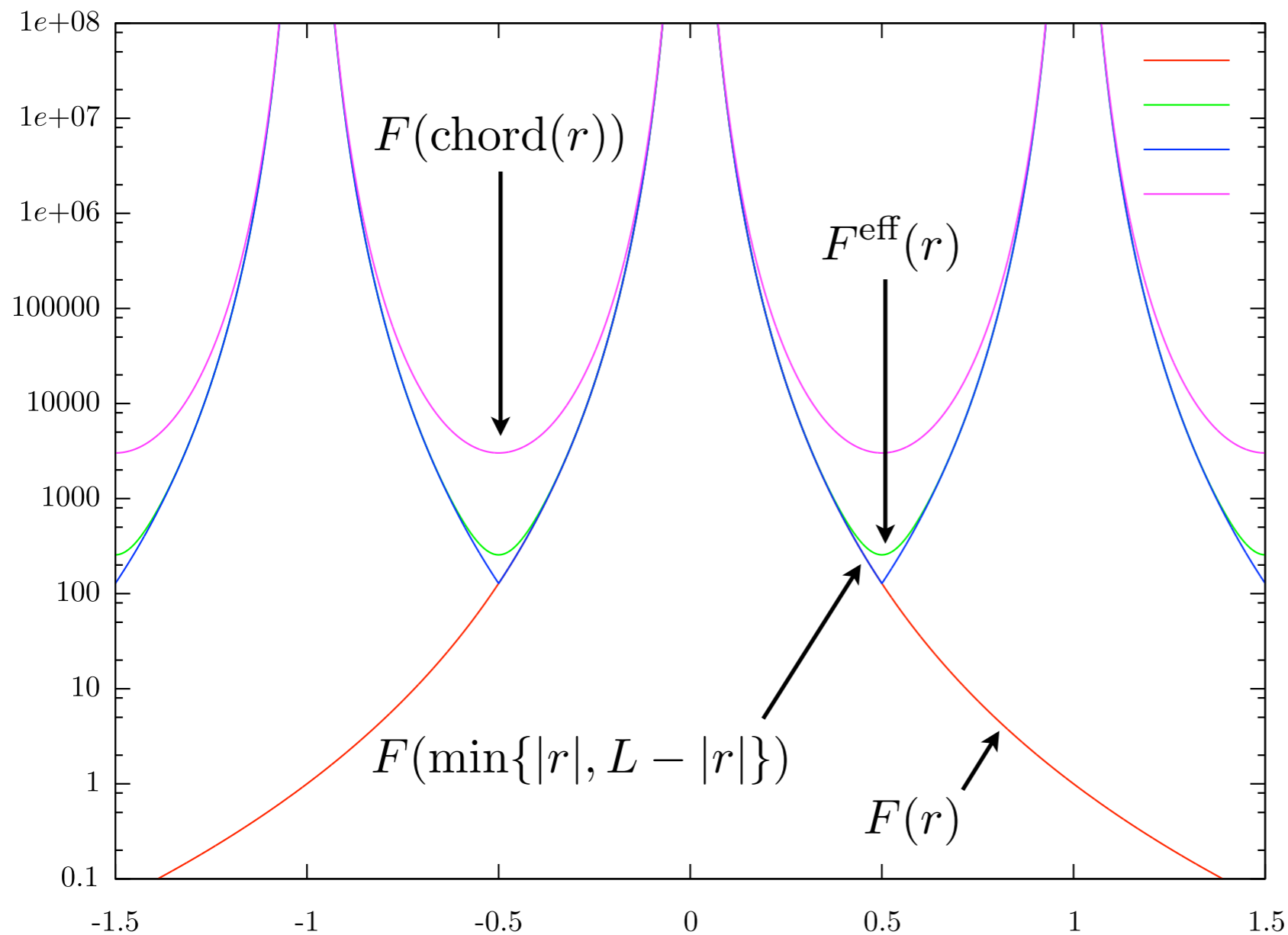
$$F^{\text{eff}}(r) = F(\text{chord}(r))$$



$$\frac{\sin(\pi r / L)}{\pi / L}$$

**chord
length**

Finite simulation cell



- ▶ **closest-image approximation increasingly good as interactions become short-ranged; e.g.,**

$$F(r) = \frac{1}{r^7}$$

Finite simulation cell

- ▶ Example distance measure in a 3D orthogonal cell

$$d_{i,j} = \left[\min\{|\Delta x|, L - |\Delta x|\}^2 + \min\{|\Delta y|, L - |\Delta y|\}^2 + \min\{|\Delta z|, L - |\Delta z|\}^2 \right]^{1/2}$$

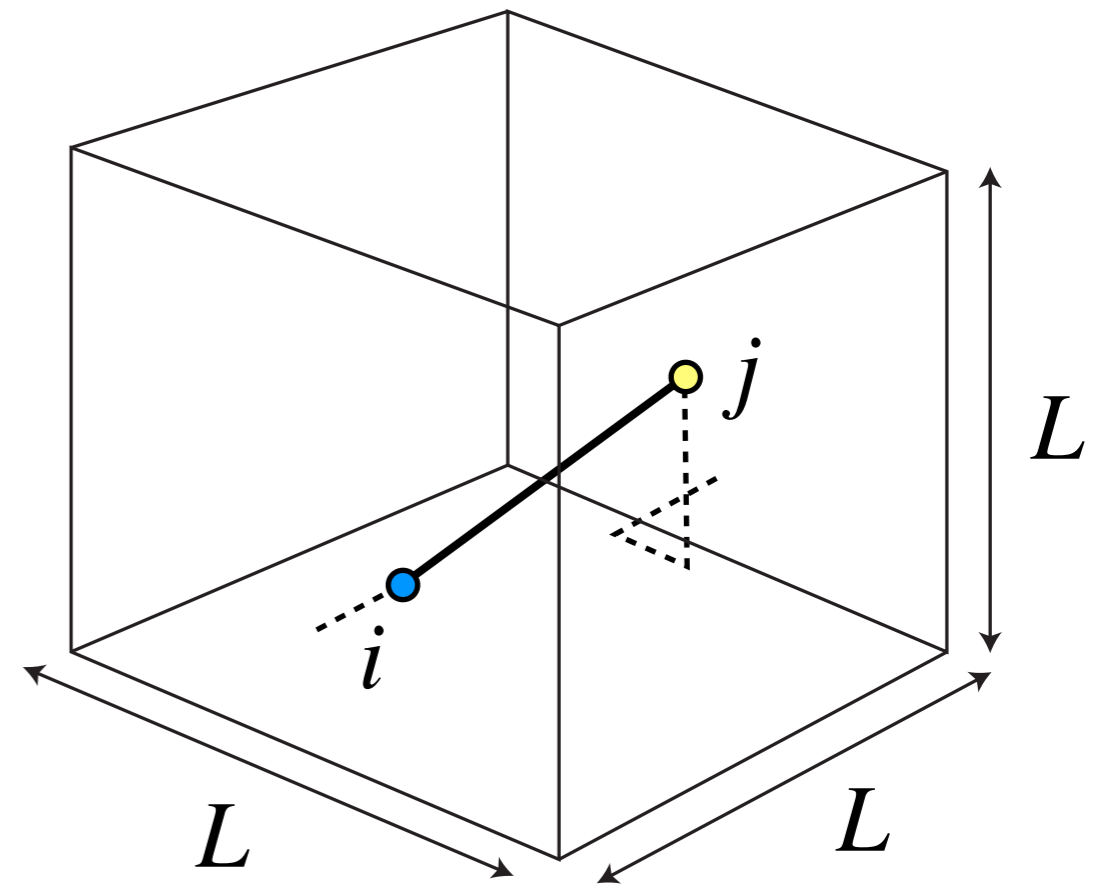
$$\Delta x = x_i - x_j$$

$$\Delta y = y_i - y_j$$

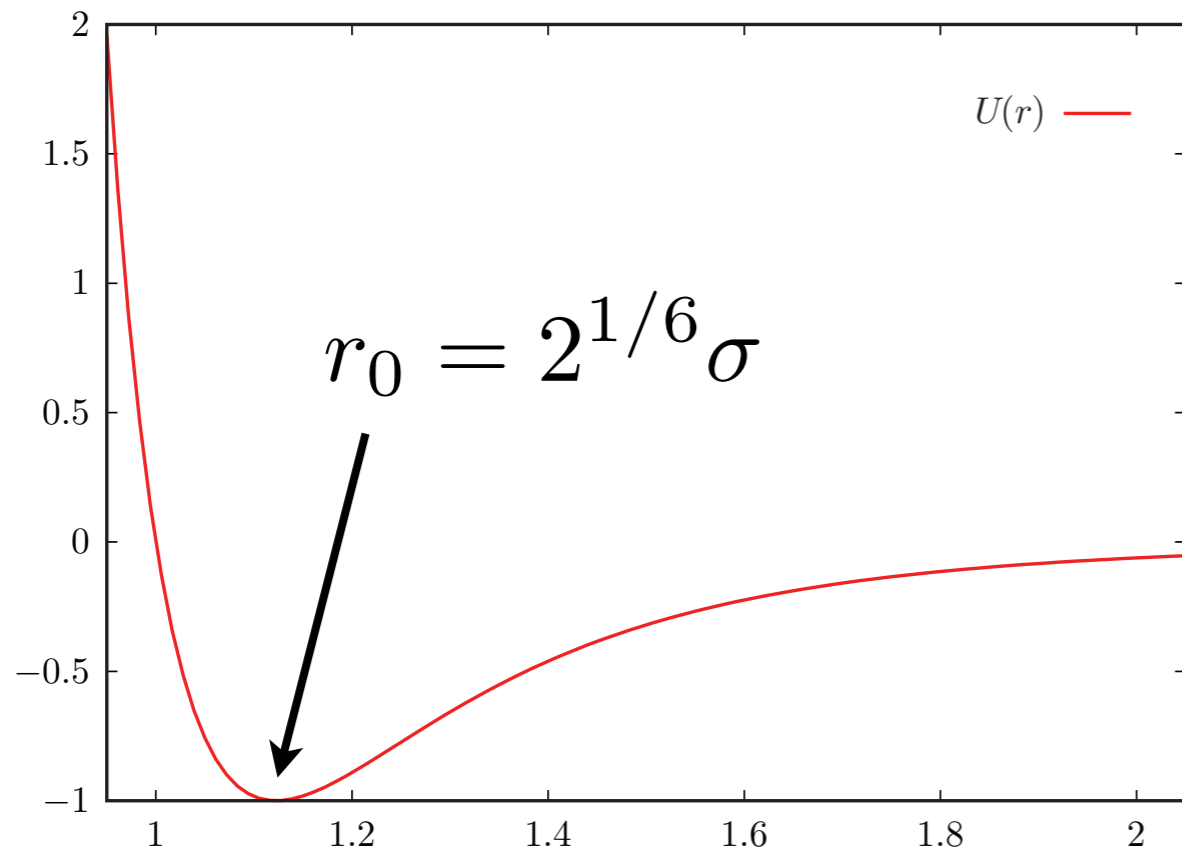
$$\Delta z = z_i - z_j$$

$$\mathbf{r}_i = (x_i, y_i, z_i)$$

$$\mathbf{r}_j = (x_j, y_j, z_j)$$



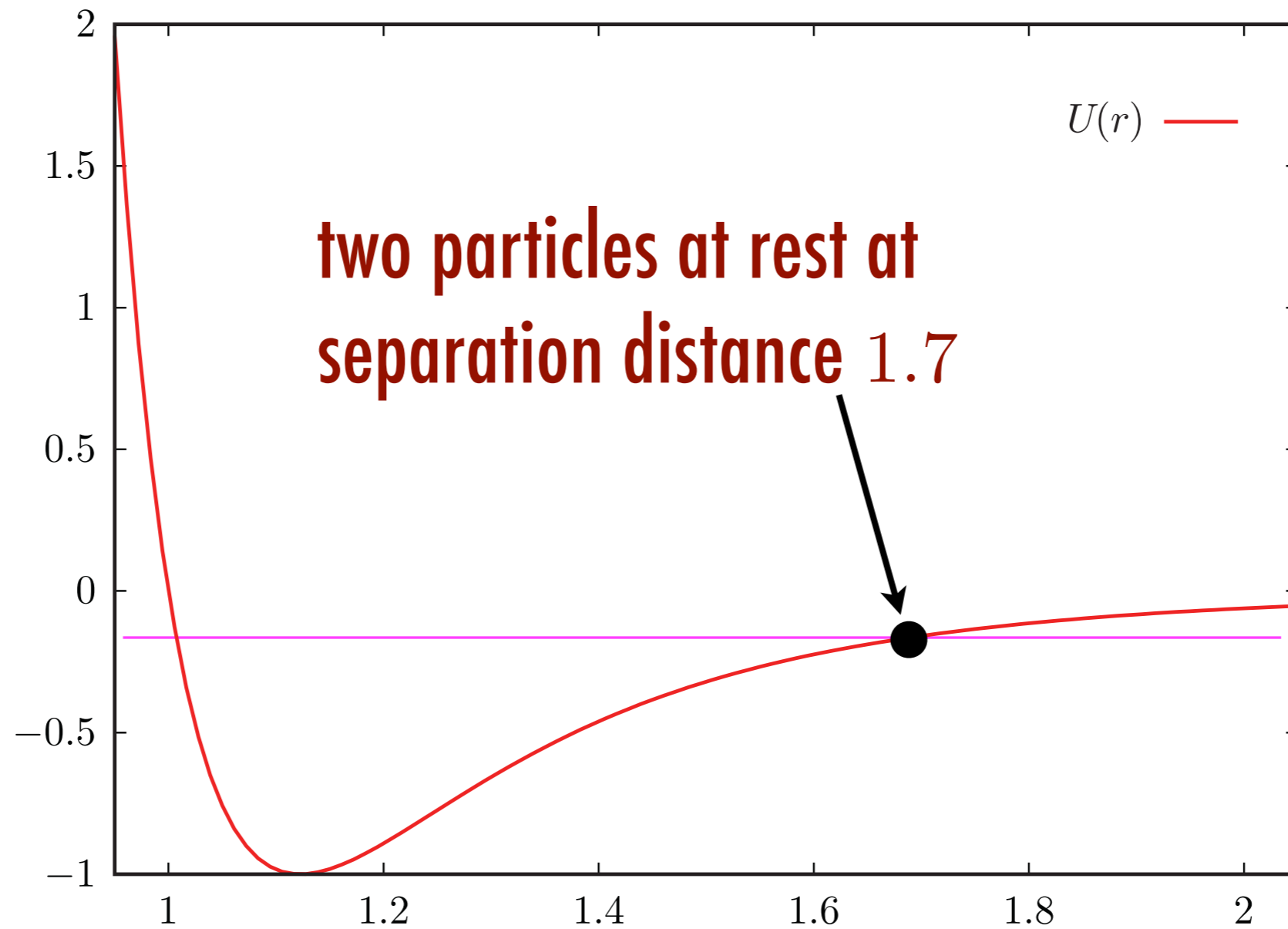
Lennard-Jones Potential



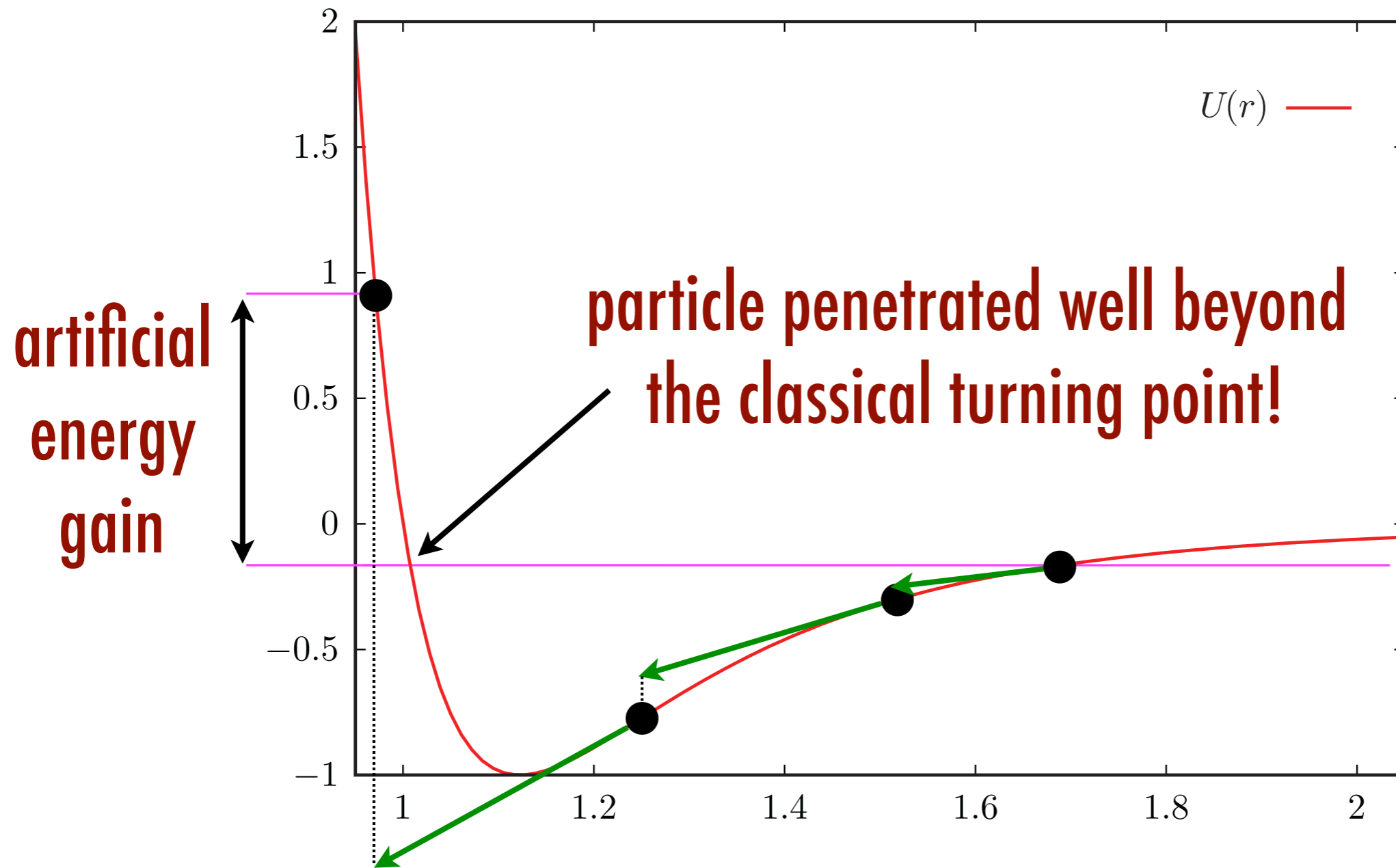
$$U(r) = 4\epsilon \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right]$$

- ▶ Model of Van der Waal's attraction between neutral atoms plus an inner core repulsion
- ▶ Equilibrium point $U'(r_0) = 0$ separates the attractive and repulsive regions

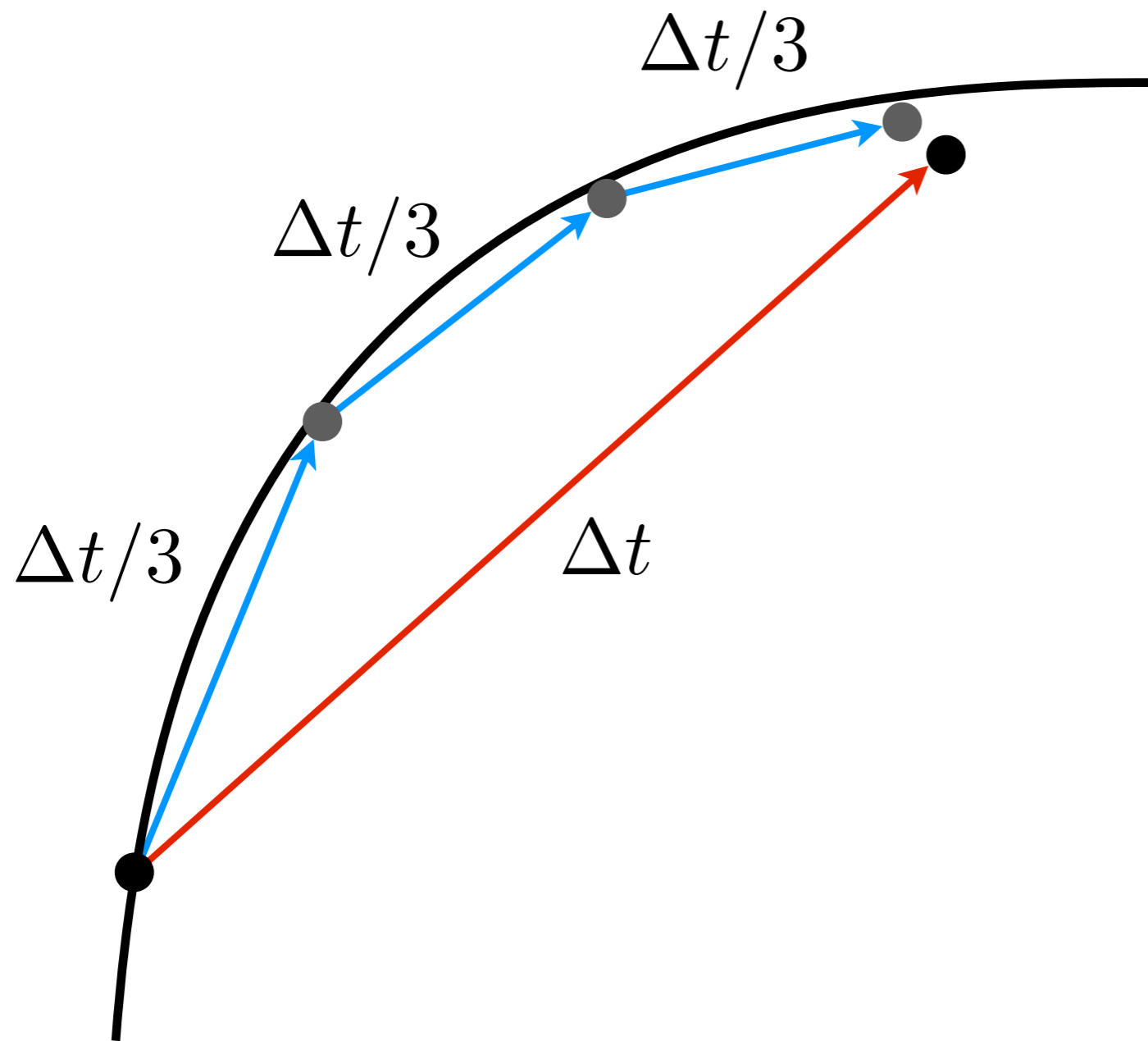
Choice of Time Step



Choice of Time Step



Adaptive Time Step



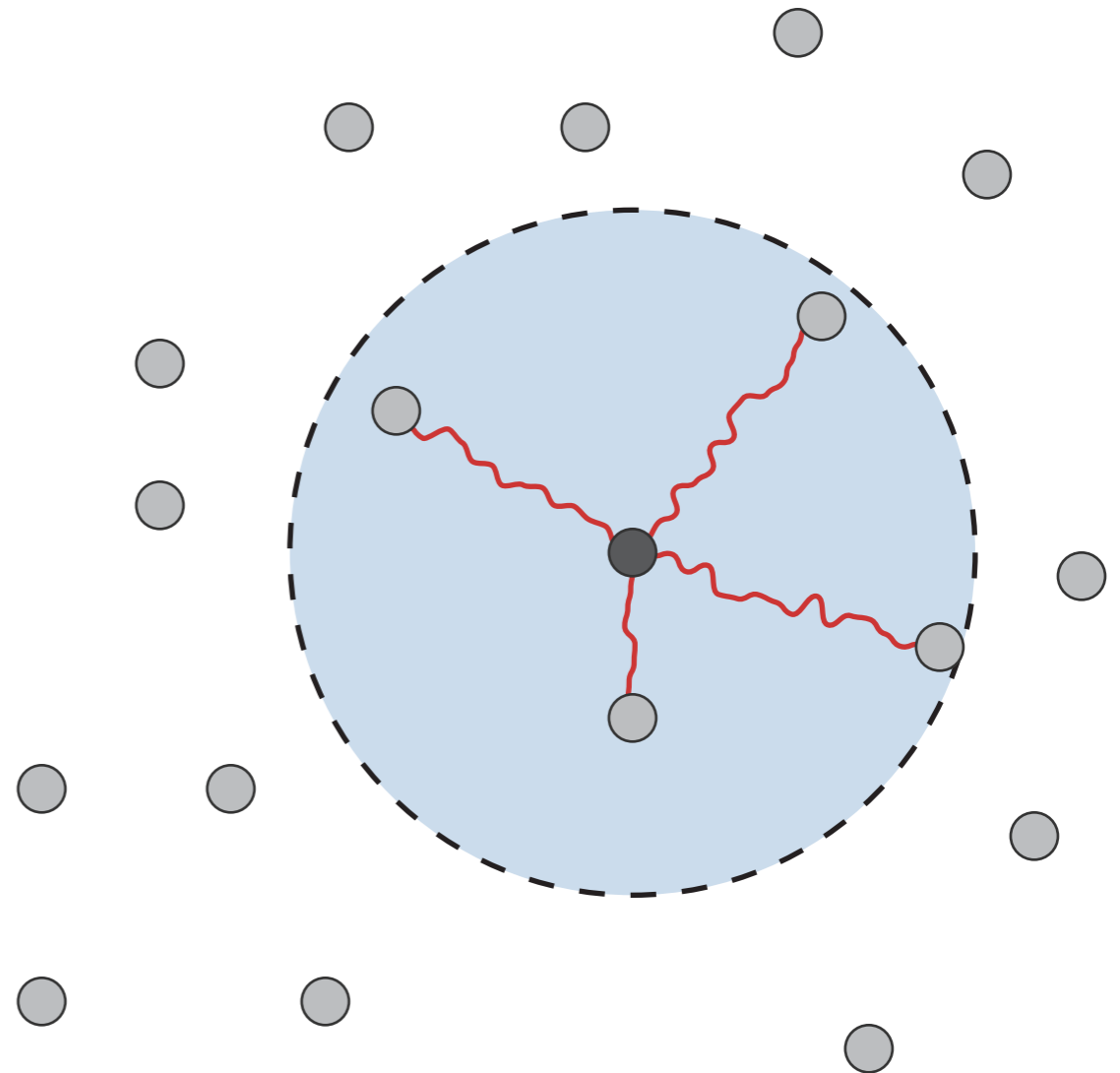
- ▶ Allow time step to vary dynamically within the simulation
- ▶ Check convergence by comparing evolution of two otherwise identical copies of the system

Range Truncation

- ▶ If interactions are finite-range, there are only a small number of forces acting on each particle (unless the particles have coalesced)
- ▶ Algorithm now scales as

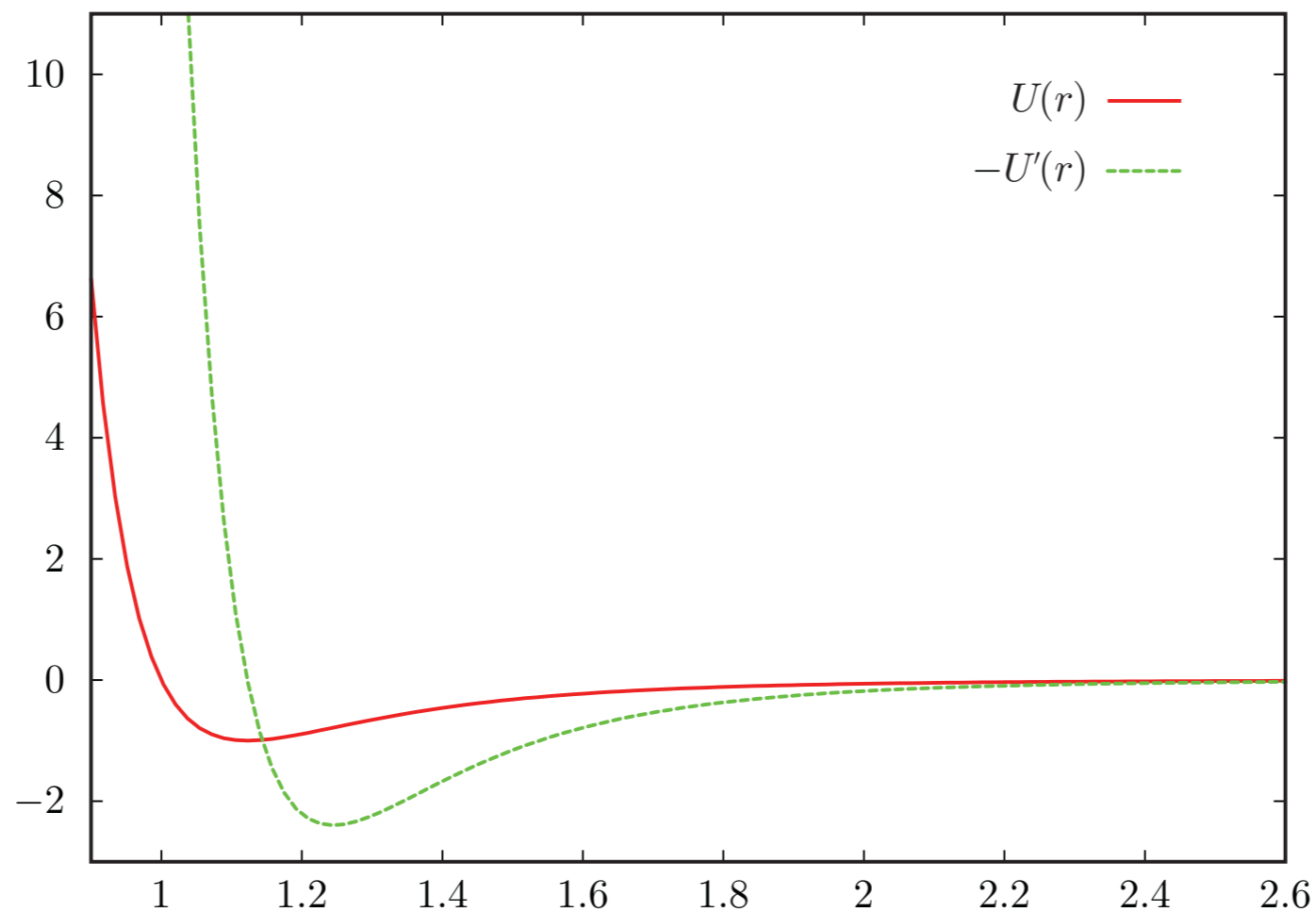
$$\frac{1}{2} \sum_{i=1}^N N_{\text{nearby}}^{(i)} \ll \frac{N(N-1)}{2}$$

- ▶ Can we impose a cutoff?



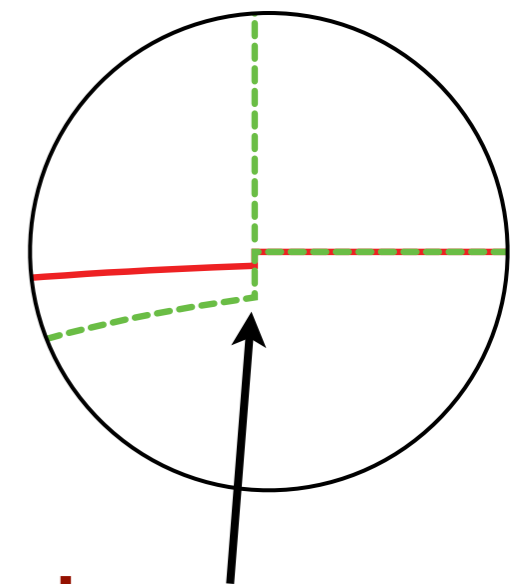
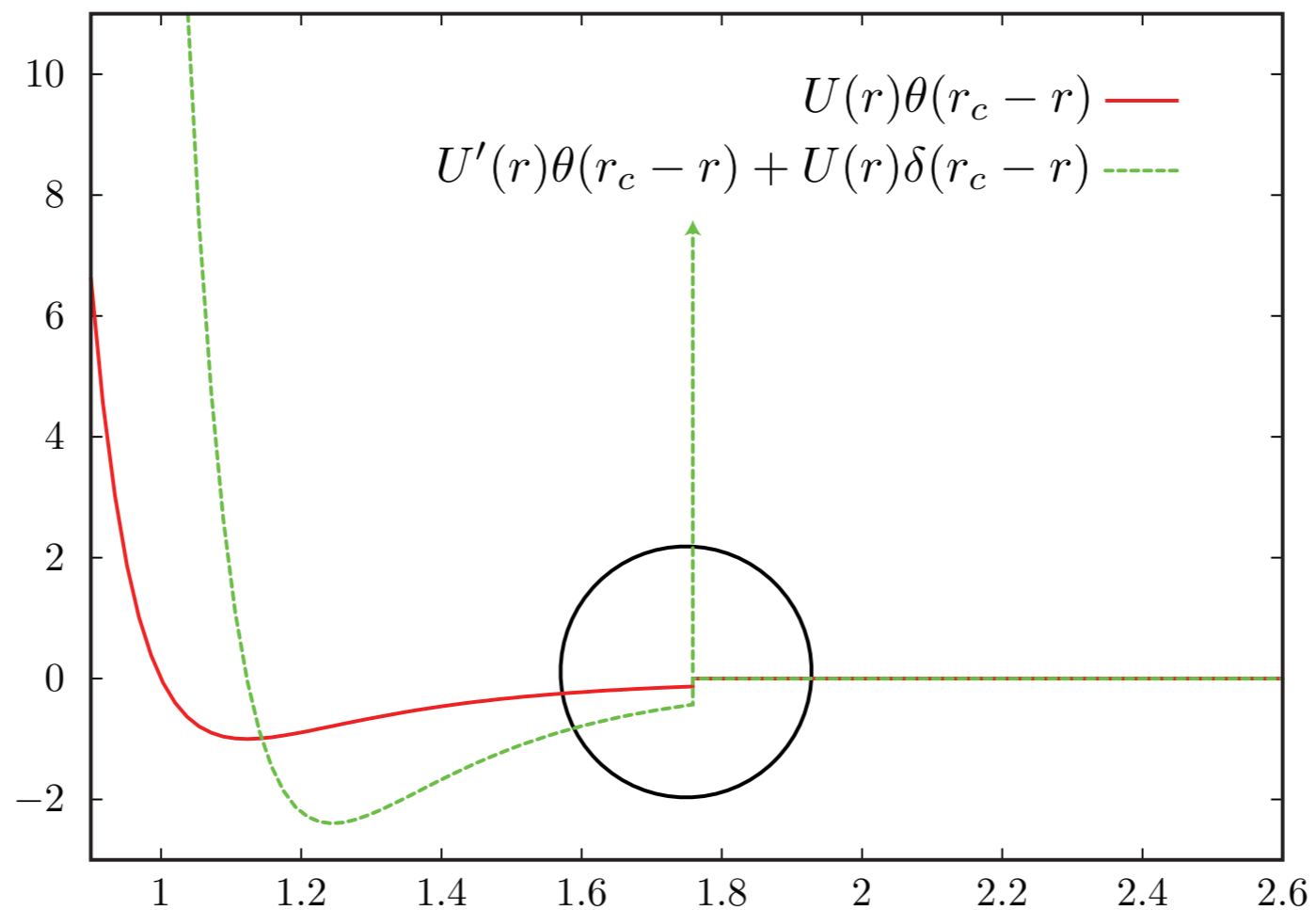
Range Truncation

- ▶ E.g., Lennard-Jones tail is very weak beyond $r_c \sim 2\sigma - 3\sigma$



Range Truncation

- ▶ Care must be taken not to introduce unphysical forces

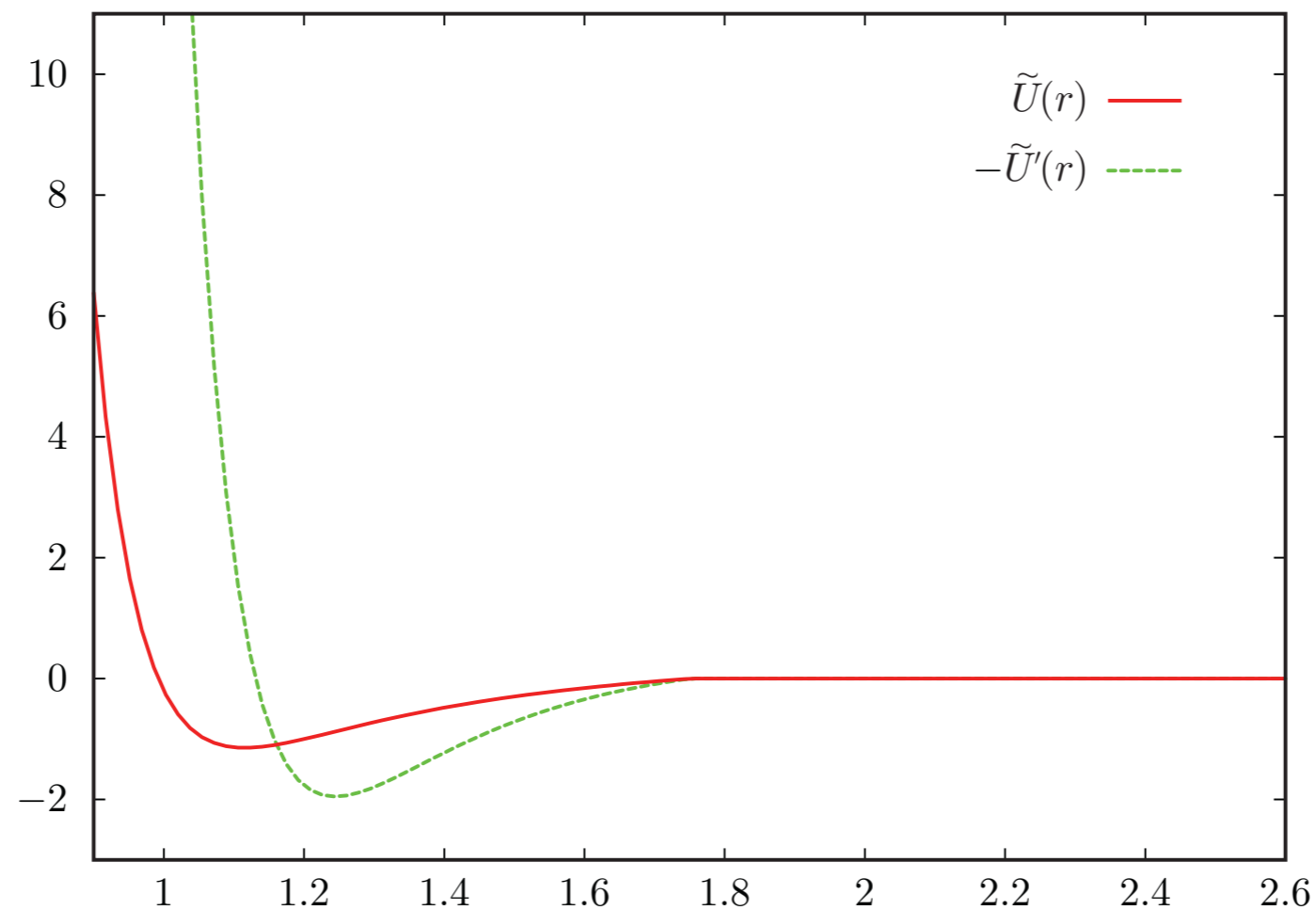


**discontinuous,
impulsive force**

Range Truncation

$$\tilde{U}(r) \equiv [U(r) - U(r_c) + (r - r_c)U'(r_c)]\theta(r_c - r)$$

$$\tilde{F}(r) = -\tilde{U}'(r) = [-U'(r) + U'(r_c)]\theta(r_c - r)$$



Ewald summation

- ▶ Naive truncation is not possible in the case of truly long-ranged interactions
- ▶ **Ewald summation** is a useful Fourier space trick
- ▶ E.g., consider non-self electrostatic interactions between particles in all image cells:

$$U_{\text{Coulomb}} = \frac{1}{2} \sum_{i,j} \sum_{\mathbf{n} \in \mathbb{Z}^3} \frac{q_i q_j (1 - \delta_{\mathbf{r}_i - \mathbf{r}_j, \mathbf{n}L})}{|\mathbf{r}_i - \mathbf{r}_j + \mathbf{n}L|}$$
$$\equiv \frac{1}{2} \sum'_{i,j,\mathbf{n}} \frac{q_i q_j}{r_{i,j,\mathbf{n}}}$$

Ewald summation

- ▶ Exact rewriting in terms of a background constant, a direct space sum, and a dual space sum:

$$U_0 = -\frac{1}{\sqrt{\pi}} \sum_i \frac{q_i^2}{\rho_0}$$

$$U_1 = \frac{1}{2} \sum_{i,j,\mathbf{n}}' q_i q_j \frac{\text{erfc}(r_{i,j,\mathbf{n}}/\rho_0)}{r_{i,j,\mathbf{n}}}$$

$$U_2 = \frac{1}{2\pi L^3} \sum_{i,j} q_i q_j \sum_{\substack{\mathbf{m} \in \mathbb{Z}^3 \\ \mathbf{m} \neq 0}} \frac{\exp[-(\pi \mathbf{m} \rho)^2 + 2\pi i \mathbf{m} \cdot (\mathbf{r}_i - \mathbf{r}_j)]}{m^2}$$

exponentially decaying envelope
real lattice
reciprocal lattice

Ewald summation

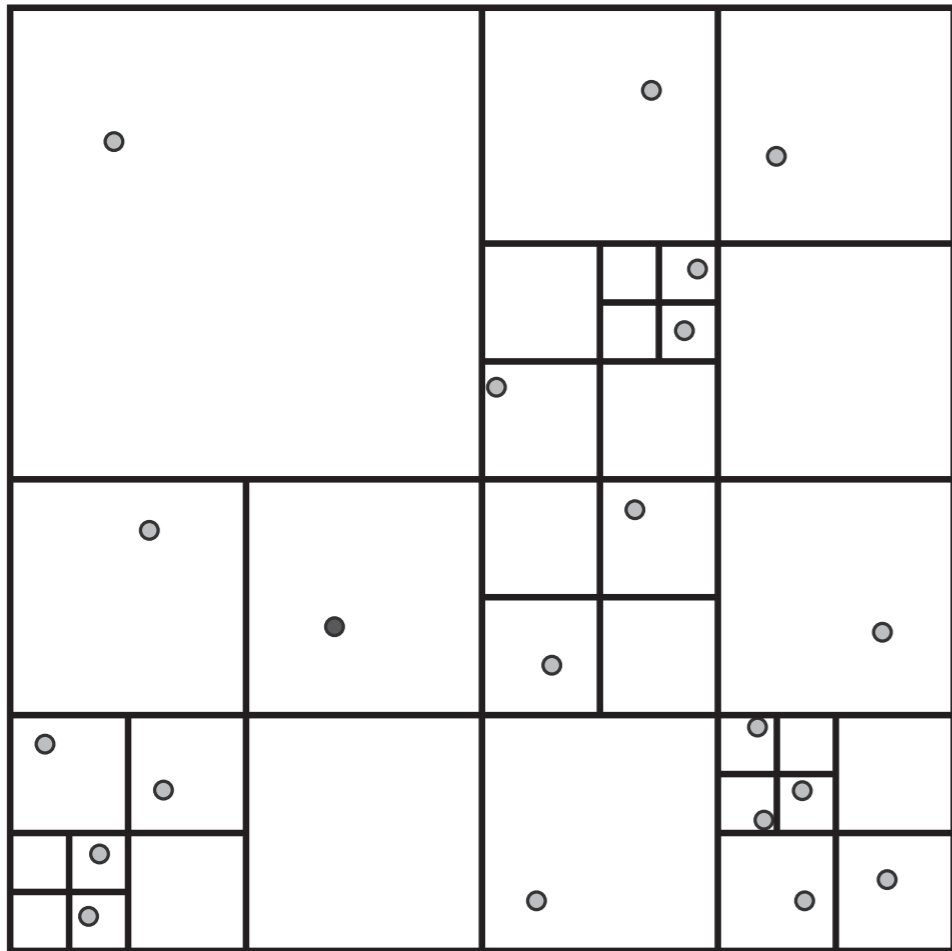
- ▶ Safe to truncate the sum in U_1 at separations above ρ_0
- ▶ Order N^2 sum over particle indices in U_2 can be evaluated as two order N sums:

$$U_2 = \frac{1}{2\pi L^3} \sum_{\mathbf{m} \neq 0} \frac{\exp \left[- (\pi \mathbf{m} \rho)^2 \right]}{\mathbf{m}^2} |S(\mathbf{m})|^2$$

$$S(\mathbf{m}) = \sum_j q_j \exp(2\pi i \mathbf{m} \cdot \mathbf{r}_j)$$

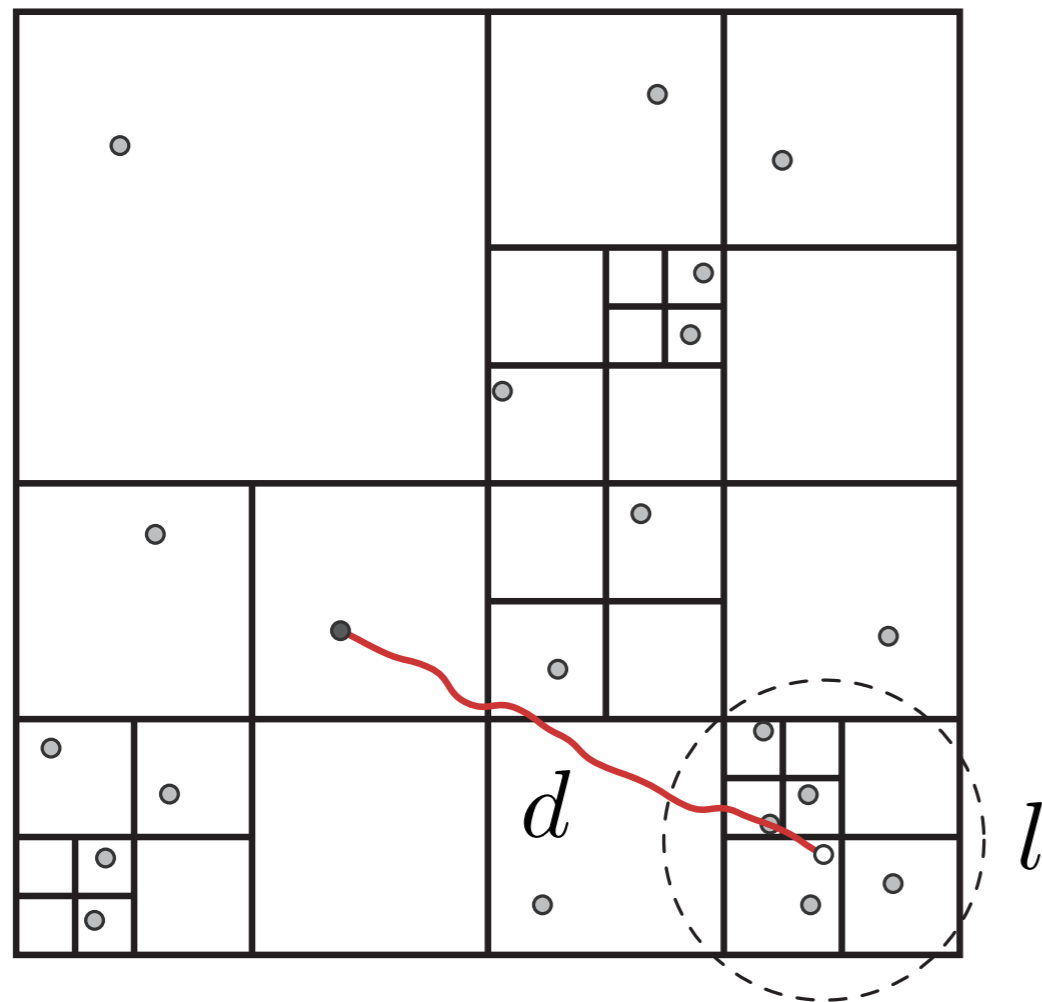
“structure factor”

Barnes-Hut tree



- ▶ dynamic data structure: recursive subdivision of space into "quads" containing at most one particle
- ▶ The centre-of-mass position is calculated at each tree level and passed up the linked-list hierarchy

Barnes-Hut tree

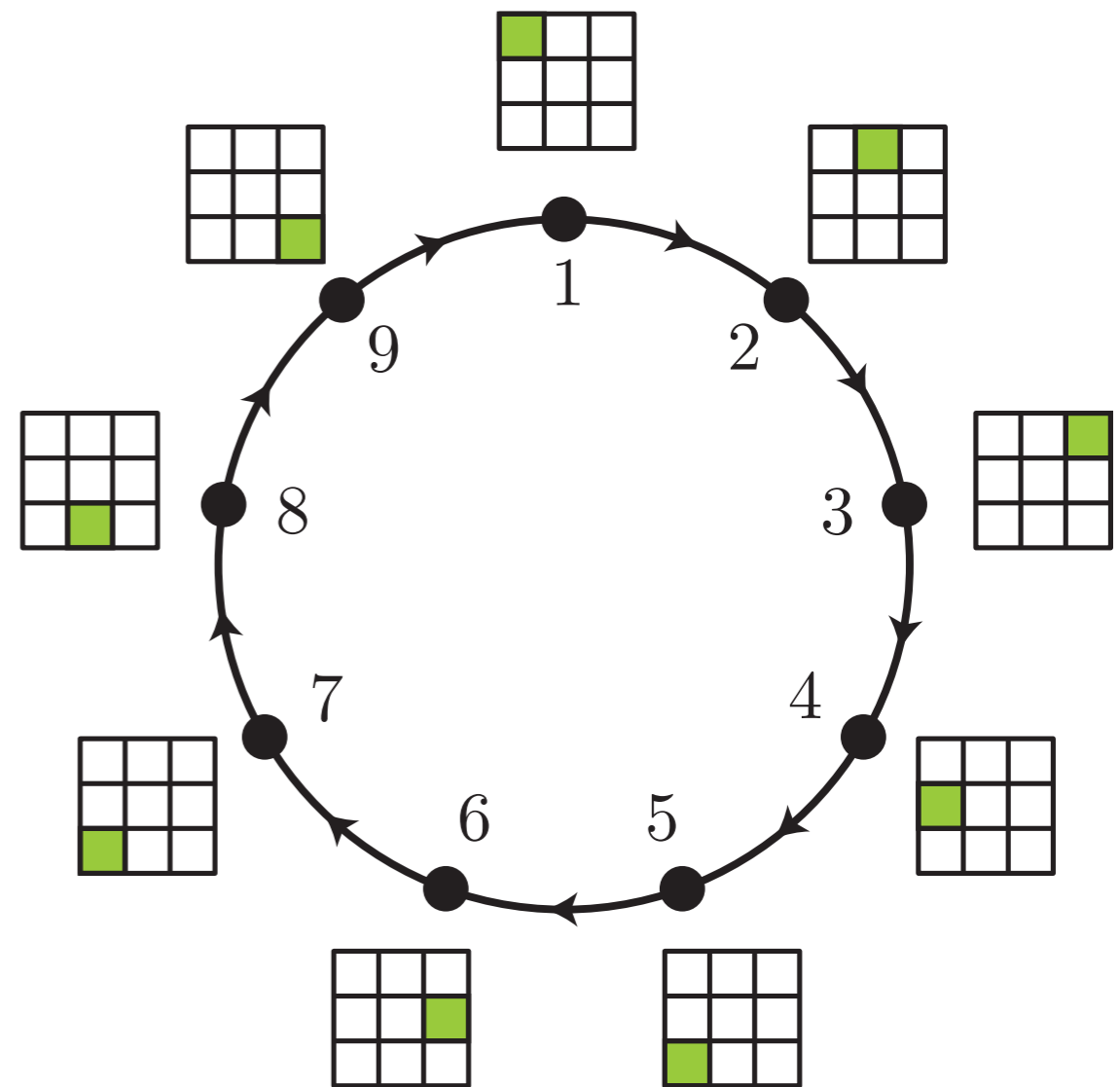


$$l/d < \theta_c$$

- ▶ Assume that a particle cluster sufficiently far away can be represented by a single representative particle at the centre-of-mass (neglects tidal forces)
- ▶ Distance judged by the size of the "opening angle"
- ▶ Scales as $N \log N$

Parallel Computation

- ▶ Simulate on many CPUs simultaneously
- ▶ Each machine updates the particles in a sub-region of the full space
- ▶ Position information passed as "messages" passed around the ring

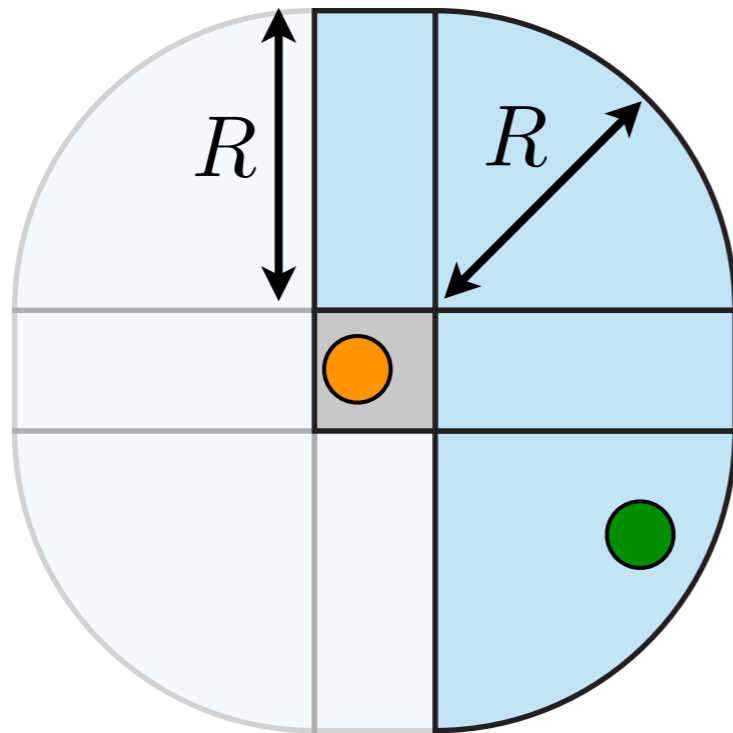


Parallel Computation

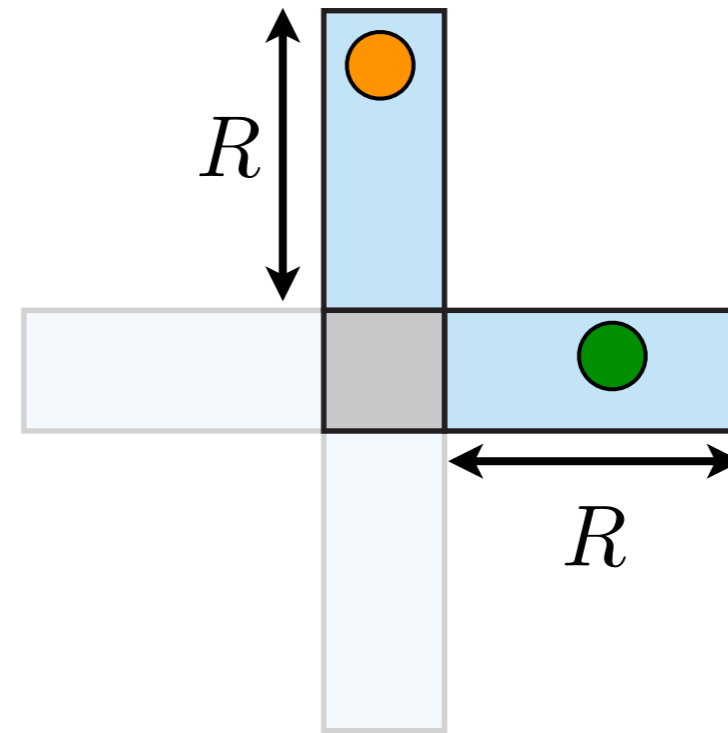
- ▶ Because of message-passing overhead, the algorithm scales somewhat worse than $N(N - 1)/2N_{\text{CPU}}$:

- Each CPU is numbered cyclically $n = 0, 1, \dots, N_{\text{CPU}} - 1$
- Loop for each time step:
 - Node n computes forces exerted by its own particles
 - Repeat $n - 1$ times:
 - * Node n sends positions to node $n + 1$ and receives positions from node $n - 1$
 - * Uses received positions to compute forces on its own particles
 - Each node updates its own positions and velocities

Neutral territory methods



traditional half-shell



neutral territory

message passing
overhead

$$\sim \frac{1}{2}\pi R^2 + 2R$$

$$\sim 2R$$