

# Experiment 6: Coefficients of Friction



Figure 6.1: Inclined Plane

## ***EQUIPMENT***

Inclined Plane  
Wood Block  
Triple-Beam Balance  
Digital Balance  
Lab Pro and Connections  
Dual-Range Force Sensor  
Masses  
Mass Hanger  
10 cm length of string

### Advance Reading

*Text:* Newton's Laws, maximum static friction, kinetic friction, coefficients of friction.

*Lab Manual:* Appendix B (Logger Pro)

### Objective

To measure and analyze the coefficients of friction  $\mu_s$  and  $\mu_k$  between a wood block and wood plane.

### Theory

Friction is the force that resists the relative motion of one surface in contact with another surface. We consider two types of friction: static and kinetic. Usually, kinetic friction is less than the maximum value of static friction.

The maximum static friction is given by:

$$F_{f_{max}} = \mu_s F_N \quad (6.1)$$

and the kinetic friction is given by:

$$F_{f_k} = \mu_k F_N \quad (6.2)$$

where  $\mu_s$  is the coefficient of static friction,  $\mu_k$  is the coefficient of kinetic friction, and  $F_N$  is the normal force.

The *angle of repose* is defined as the maximum angle at which an object on an inclined plane will retain its position without tending to slide. It can be shown that the tangent of this angle equals  $\mu_s$ :

$$\tan \theta = \mu_s \quad (6.3)$$

Similarly, it can also be shown that when an object slides down an incline at constant velocity:

$$\tan \theta = \mu_k \quad (6.4)$$

In this experiment, the frictional force between a wooden block and the wooden surface of a horizontal and inclined plane will be derived and measured. By graphing these data, coefficients of static and kinetic friction will be obtained.

As you perform this experiment, theoretical quantities will be determined prior to measuring for *Part 2* through *Part 5*. These calculations will require the free-body diagram solution method (refer to Page 28).

## Experiment 6: Coefficients of Friction

When  $a = 0.0 \text{ m/s}^2$ , the force probe measures the force necessary to counteract friction and thus is equal to  $F_f$ .

If the block is pulled at constant velocity, starting from rest, there is a “bump” at the beginning of the graph, and the remaining graph is, on average, horizontal.

The bump at the beginning of the graph is a result of overcoming the maximum static friction,  $F_{f_{max}}$ , which is usually greater than kinetic friction,  $F_{f_k}$ . The maximum value of this bump allows us to determine  $\mu_s$ . The horizontal portion of the graph,  $F_{f_{avg}}$ , allows us to determine  $\mu_k$ . A sketch of how your graph should look is shown in Fig. 6.2. Note that the force begins at zero newtons, which will require you to leave slack in the string until data is being collected.

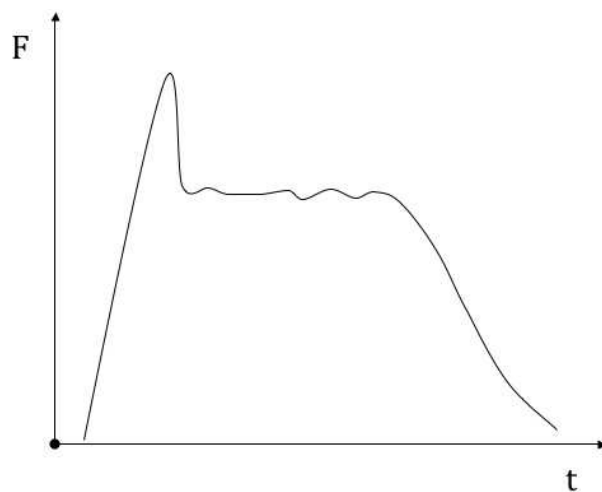


Figure 6.2: Sample *Force vs. Time* graph



**PROCEDURE****PART 1: Preparation**

1. For all calculations involving forces, always use the free-body diagram solution method provided on Page 28.
2. Consider a wood block being pulled horizontally at a constant velocity. Derive the equation of force,  $T$ , in terms of the following quantities:  $m$ ,  $g$ ,  $\mu$ ,  $\theta$ .
3. Ask your TA to check your equation before proceeding.
4. Refer to *Appendix B* for *Logger Pro* information. Open “12a Static Kinetic Frict.cmbl.” A window will open as a  $F$  vs.  $t$  graph.
5. Calibrate the force sensor: *Experiment*  $\Rightarrow$  *Calibrate*  $\Rightarrow$  *Lab Pro*. The window has four tabs at the top. Choose *Calibrate*. Click on “Calibrate Now.”

*Reading 1:*

6. Calculate and enter the force due to 0.00 kg. Hold the sensor steady, supported vertically against the table edge. Select *Keep*.

*Reading 2:*

7. Measure, then suspend 0.55 kg from the sensor.
8. Calculate and enter the force due to 0.55 kg. Hold the sensor steady. Select *Keep*, then *OK*.
9. Test the calibration: Click *Collect* while suspending 0.55 kg from the force probe. The graph should plot the correct amount of force. If it does not, then there is a problem. First, re-calibrate. If that isn't sufficient, refer to *Appendix B*.

**PART 2: Block on a Horizontal Plane:  $\theta = 0^\circ$** 

10. You will need to understand *Step 11* through *Step 14* before collecting data.
11. Always leave slack in the string until the collection of data begins.
12. Technique will be important for this experiment. You will want to use the same part of the inclined plane for all parts of the experiment; keep the string parallel to the surface of the inclined plane while pulling the block, and pull the block at a constant velocity.

13. A few trials using small and large diameter masses prior to collecting data will yield more accurate results.
14. You will need to determine for each trial  $f_{max}$ ,  $f_k$ , and  $F_N$  (details follow):
  - To determine the graph value of  $f_{max}$ , use the *Examine* button, then position the cursor at the highest peak.
  - To determine  $f_k$ , click-and-drag the mouse to select the constant force section of the graph, then use the *Stats* button.
  - To determine  $F_N$ , refer to your free-body diagram solutions.
15. Measure all masses!
16. Define  $g = (9.80 \pm 0.01) \text{ m/s}^2$
17. Measure the mass  $m = (\text{block} + 0.5 \text{ kg})$ .
18. Attach the string from the block to the force sensor. Click *Collect*. Pull  $m$  (block + 0.5 kg) across the plane at a constant velocity.
19. Determine  $f_{max}$ ,  $f_k$ , and  $F_N$ .
20. Increase  $m$  for each trial, in increments of 0.5 kg, until a total of 2.5 kg has been added.

**PART 3: Block on an Inclined Plane:  $\theta = 30^\circ$** 

21. Derive  $T$  (algebraically) for an object of mass  $m$  being pulled up an inclined (angle  $\theta$ ) at constant velocity (quantities as before).
22. Use the force probe to measure  $T$  for this situation ( $\theta = 30^\circ$ ,  $m = (\text{block} + 0.5) \text{ kg}$ )

**PART 4: Coefficient of Static Friction**

23. Measure the angle of repose by slowly raising the inclined plane until the (block + 0.5 kg) just begins to slide.
24. Calculate  $\mu_s$  from the measured angle (Eq. 6.3).

**PART 5: Coefficient of Kinetic Friction**

25. Measure the angle that the (block + 0.5 kg), when tapped, slides *without acceleration*.

26. It can be shown that when an object slides without acceleration after being tapped, then  $\tan \theta = \mu_k$ . Calculate  $\mu_k$  from the measured angle.

**PART 6: Graphing**

27. Plot  $f_{max}$  vs.  $F_N$  and  $f_k$  vs.  $F_N$  on the same graph.  
28. What do the slopes represent?

**PART 7: Analysis**

29. Derive the angle of repose equation for an object of mass  $m$  (Eq. 6.3).  
30. It can be shown that when an object is lightly tapped, then slides *without acceleration*,  $\mu_k = \tan \theta$ . Derive this equation.  
31. Calculate  $T$  from *Part 3* using your graph value of  $\mu_k$ .  
32. Compare  $\mu_s$  values obtained from *Part 4* and *Part 6*.  
33. Compare  $\mu_k$  values obtained from *Part 5* and *Part 6*.

**QUESTIONS**

1. Show that  $\mu_s = \tan \theta$  for the angle of repose. Refer to Page 28.
2. If the mass of the block is tripled, does the angle of repose change?
3. Why was it necessary to tap the block to get it started in *Part 5*?
4. Why can anti-lock brakes stop a car in a shorter distance than regular brakes? (Comment on the difference between static and kinetic friction.)
5. Compare the graph and experimental values for the coefficients of friction. Is  $\mu_s > \mu_k$  for each method?