

Chapter 7

10. The change in kinetic energy can be written as

$$\Delta K = \frac{1}{2} m(v_f^2 - v_i^2) = \frac{1}{2} m(2a\Delta x) = ma\Delta x$$

where we have used $v_f^2 = v_i^2 + 2a\Delta x$ from Table 2-1. From Fig. 7-27, we see that $\Delta K = (0 - 30) \text{ J} = -30 \text{ J}$ when $\Delta x = +5 \text{ m}$. The acceleration can then be obtained as

$$a = \frac{\Delta K}{m\Delta x} = \frac{(-30 \text{ J})}{(8.0 \text{ kg})(5.0 \text{ m})} = -0.75 \text{ m/s}^2.$$

The negative sign indicates that the mass is decelerating. From the figure, we also see that when $x = 5 \text{ m}$ the kinetic energy becomes zero, implying that the mass comes to rest momentarily. Thus,

$$v_0^2 = v^2 - 2a\Delta x = 0 - 2(-0.75 \text{ m/s}^2)(5.0 \text{ m}) = 7.5 \text{ m}^2/\text{s}^2,$$

or $v_0 = 2.7 \text{ m/s}$. The speed of the object when $x = -3.0 \text{ m}$ is

$$v = \sqrt{v_0^2 + 2a\Delta x} = \sqrt{7.5 + 2(-0.75)(-3.0)} = \sqrt{12} = 3.5 \text{ m/s}.$$

11. We choose $+x$ as the direction of motion (so \vec{a} and \vec{F} are negative-valued).

(a) Newton's second law readily yields $\vec{F} = (85 \text{ kg})(-2.0 \text{ m/s}^2)$ so that

$$F = |\vec{F}| = 1.7 \times 10^2 \text{ N}.$$

(b) From Eq. 2-16 (with $v = 0$) we have

$$0 = v_0^2 + 2a\Delta x \Rightarrow \Delta x = -\frac{(37 \text{ m/s})^2}{2(-2.0 \text{ m/s}^2)} = 3.4 \times 10^2 \text{ m}.$$

Alternatively, this can be worked using the work-energy theorem.

(c) Since \vec{F} is opposite to the direction of motion (so the angle ϕ between \vec{F} and $\vec{d} = \Delta x$ is 180°) then Eq. 7-7 gives the work done as $W = -F\Delta x = -5.8 \times 10^4 \text{ J}$.

(d) In this case, Newton's second law yields $\vec{F} = (85 \text{ kg})(-4.0 \text{ m/s}^2)$ so that $F = |\vec{F}| = 3.4 \times 10^2 \text{ N}$.

(e) From Eq. 2-16, we now have

$$\Delta x = -\frac{(37 \text{ m/s})^2}{2(-4.0 \text{ m/s}^2)} = 1.7 \times 10^2 \text{ m}.$$

(f) The force \vec{F} is again opposite to the direction of motion (so the angle ϕ is again 180°) so that Eq. 7-7 leads to $W = -F\Delta x = -5.8 \times 10^4 \text{ J}$. The fact that this agrees with the result of part (c) provides insight into the concept of work.

15. Using the work-kinetic energy theorem, we have

$$\Delta K = W = \vec{F} \cdot \vec{d} = Fd \cos \phi$$

In addition, $F = 12 \text{ N}$ and $d = \sqrt{(2.00)^2 + (-4.00)^2 + (3.00)^2} = 5.39 \text{ m}$.

(a) If $\Delta K = +30.0 \text{ J}$, then

$$\phi = \cos^{-1}\left(\frac{\Delta K}{Fd}\right) = \cos^{-1}\left(\frac{30.0}{(12.0)(5.39)}\right) = 62.3^\circ.$$

(b) $\Delta K = -30.0 \text{ J}$, then

$$\phi = \cos^{-1}\left(\frac{\Delta K}{Fd}\right) = \cos^{-1}\left(\frac{-30.0}{(12.0)(5.39)}\right) = 118^\circ$$

21. Eq. 7-15 applies, but the wording of the problem suggests that it is only necessary to examine the contribution from the rope (which would be the " W_a " term in Eq. 7-15):

$$W_a = -(50 \text{ N})(0.50 \text{ m}) = -25 \text{ J}$$

(the minus sign arises from the fact that the pull from the rope is anti-parallel to the direction of motion of the block). Thus, the kinetic energy would have been 25 J greater if the rope had not been attached (given the same displacement).

35. We choose to work this using Eq. 7-10 (the work-kinetic energy theorem). To find the initial and final kinetic energies, we need the speeds, so

$$v = \frac{dx}{dt} = 3.0 - 8.0t + 3.0t^2$$

in SI units. Thus, the initial speed is $v_i = 3.0 \text{ m/s}$ and the speed at $t = 4 \text{ s}$ is $v_f = 19 \text{ m/s}$. The change in kinetic energy for the object of mass $m = 3.0 \text{ kg}$ is therefore

$$\Delta K = \frac{1}{2} m (v_f^2 - v_i^2) = 528 \text{ J}$$

which we round off to two figures and (using the work-kinetic energy theorem) conclude that the work done is $W = 5.3 \times 10^2 \text{ J}$.

37. (a) We first multiply the vertical axis by the mass, so that it becomes a graph of the applied force. Now, adding the triangular and rectangular “areas” in the graph (for $0 \leq x \leq 4$) gives 42 J for the work done.

(b) Counting the “areas” under the axis as negative contributions, we find (for $0 \leq x \leq 7$) the work to be 30 J at $x = 7.0 \text{ m}$.

(c) And at $x = 9.0 \text{ m}$, the work is 12 J.

(d) Eq. 7-10 (along with Eq. 7-1) leads to speed $v = 6.5 \text{ m/s}$ at $x = 4.0 \text{ m}$. Returning to the original graph (where a was plotted) we note that (since it started from rest) it has received acceleration(s) (up to this point) only in the $+x$ direction and consequently must have a velocity vector pointing in the $+x$ direction at $x = 4.0 \text{ m}$.

(e) Now, using the result of part (b) and Eq. 7-10 (along with Eq. 7-1) we find the speed is 5.5 m/s at $x = 7.0 \text{ m}$. Although it has experienced some deceleration during the $0 \leq x \leq 7$ interval, its velocity vector still points in the $+x$ direction.

(f) Finally, using the result of part (c) and Eq. 7-10 (along with Eq. 7-1) we find its speed $v = 3.5 \text{ m/s}$ at $x = 9.0 \text{ m}$. It certainly has experienced a significant amount of deceleration

during the $0 \leq x \leq 9$ interval; nonetheless, its velocity vector *still* points in the $+x$ direction.

41. The power associated with force \vec{F} is given by $P = \vec{F} \cdot \vec{v}$, where \vec{v} is the velocity of the object on which the force acts. Thus,

$$P = \vec{F} \cdot \vec{v} = Fv \cos \phi = (122 \text{ N})(5.0 \text{ m/s}) \cos 37^\circ = 4.9 \times 10^2 \text{ W}.$$

48. (a) With SI units understood, the object's displacement is

$$\vec{d} = \vec{d}_f - \vec{d}_i = -8.00 \hat{i} + 6.00 \hat{j} + 2.00 \hat{k}.$$

Thus, Eq. 7-8 gives $W = \vec{F} \cdot \vec{d} = (3.00)(-8.00) + (7.00)(6.00) + (7.00)(2.00) = 32.0 \text{ J}$.

(b) The average power is given by Eq. 7-42:

$$P_{\text{avg}} = \frac{W}{t} = \frac{32.0}{4.00} = 8.00 \text{ W}.$$

(c) The distance from the coordinate origin to the initial position is $d_i = \sqrt{(3.00)^2 + (-2.00)^2 + (5.00)^2} = 6.16 \text{ m}$, and the magnitude of the distance from the coordinate origin to the final position is $d_f = \sqrt{(-5.00)^2 + (4.00)^2 + (7.00)^2} = 9.49 \text{ m}$. Their scalar (dot) product is

$$\vec{d}_i \cdot \vec{d}_f = (3.00)(-5.00) + (-2.00)(4.00) + (5.00)(7.00) = 12.0 \text{ m}^2.$$

Thus, the angle between the two vectors is

$$\phi = \cos^{-1} \left(\frac{\vec{d}_i \cdot \vec{d}_f}{d_i d_f} \right) = \cos^{-1} \left(\frac{12.0}{(6.16)(9.49)} \right) = 78.2^\circ.$$

49. From Eq. 7-32, we see that the “area” in the graph is equivalent to the work done. We find the area in terms of rectangular [length \times width] and triangular [$\frac{1}{2}$ base \times height] areas and use the work-kinetic energy theorem appropriately. The initial point is taken to be $x = 0$, where $v_0 = 4.0 \text{ m/s}$.

(a) With $K_i = \frac{1}{2}mv_0^2 = 16 \text{ J}$, we have

$$K_3 - K_0 = W_{0 < x < 1} + W_{1 < x < 2} + W_{2 < x < 3} = -4.0 \text{ J}$$

so that K_3 (the kinetic energy when $x = 3.0 \text{ m}$) is found to equal 12 J.

(b) With SI units understood, we write $W_{3 < x < x_f}$ as $F_x \Delta x = (-4.0)(x_f - 3.0)$ and apply the work-kinetic energy theorem:

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so that the requirement $K_{x_f} = 8.0 \text{ J}$ leads to $x_f = 4.0 \text{ m}$.

(c) As long as the work is positive, the kinetic energy grows. The graph shows this situation to hold until $x = 1.0 \text{ m}$. At that location, the kinetic energy is

$$K_1 = K_0 + W_{0 < x < 1} = 16 \text{ J} + 2.0 \text{ J} = 18 \text{ J}.$$