

# Experiment 11: Simple Harmonic Motion



Figure 11.1

## ***EQUIPMENT***

Spring  
Metal Ball  
Wood Ball  
(*Note: sharp hooks*)  
Meter Stick  
Digital Balance  
Stopwatch  
Pendulum Clamp and Rod  
String  
Masses: (2) 100g, (1) 50g  
Mass Hanger  
Table Clamp  
Protractor

### Advance Reading

*Text:* Simple harmonic motion, oscillations, wavelength, frequency, period, Hooke's Law.

*Lab Manual:* Appendix C

### Objective

To investigate simple harmonic motion using a simple pendulum and an oscillating spring; to determine the spring constant of a spring.

### Theory

Periodic motion is “motion of an object that regularly returns to a given position after a fixed time interval.” *Simple harmonic motion* is a special kind of periodic motion in which the object oscillates sinusoidally, smoothly. Simple harmonic motion arises whenever an object is returned to the equilibrium position by a *restorative force* proportional to the object's displacement.

$$F = -kx \quad (11.1)$$

The illustrative example above is *Hooke's Law*, which describes the restorative force of an oscillating spring of stiffness  $k$  (spring constant).

For an ideal, massless spring that obeys Hooke's Law, the time required to complete an oscillation (period,  $T$ , seconds) depends on the spring constant and the mass,  $m$ , of an object suspended at one end:

$$T = 2\pi\sqrt{\frac{m}{k}} \quad (11.2)$$

The inverse of period is the frequency of oscillation. Recall that frequency,  $f$ , is the number of oscillations completed by a system every second. The standard unit for frequency is hertz, Hz (inverse second,  $s^{-1}$ ).

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The period of oscillation of an ideal, simple pendulum depends on the length,  $L$ , of the pendulum and the acceleration due to gravity,  $g$ :

$$T = 2\pi\sqrt{\frac{L}{g}} \quad (11.3)$$

When setting the pendulum in motion, small displacements are required to ensure simple harmonic motion. Large displacements exhibit more complex, sometimes chaotic, motion. Simple harmonic motion governs where the *small angle approximation* is valid:

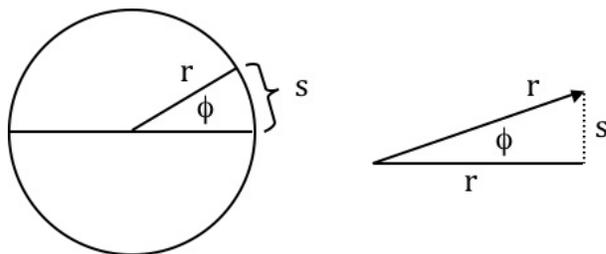


Figure 11.2: Small Angle Approximation

The arc length,  $s$ , of a circle of radius  $r$  is:

$$s = r\phi \quad (11.4)$$

When  $\phi$  is small, the arc length is approximately equal to a straight line segment that joins the two points. Therefore, the following approximations are valid:

$$\phi \approx \sin \phi \approx \tan \phi \quad (11.5)$$