# RIGID SURFACES IN GENERAL RELATIVITY

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### OUTLINE

 Motivation: Defining energy with the thin shell formalism  Rigid Surfaces: Definition, Initial Value Formulation, and Applications

# NOTATION



- *M* is 4d spacetime with coords x<sup>µ</sup> and signature (-,+,+,+)
- *H* is hypersurface of *M* with timelike tangent vector
- Spacelike hypersurfaces of
   *H* will be called *S*
- σ<sub>AB</sub> is induced metric on S
  y<sup>A</sup> → coordinates on S
  y<sup>a</sup> = (τ, y<sup>A</sup>) → coords. on H

# **GLUING SPACETIMES**



- Let *H* spatially enclose a region of spacetime (for spatial sections *S*, *∃* ∂*S*)
- Try to isometrically embed *H* in flat spacetime
- If successful, one can "glue" region of curved spacetime *M*<sub>-</sub> to region of flat spacetime *M*<sub>+</sub> at boundary *H*
- +, subscripts denote qtys defined on different sides of *H*

#### THIN SHELL FORMALISM

Using the thin-shell formalism, one can define a surface stress tensor \$\mathcal{T}\_{ab}\$ on \$\mathcal{H}\$:

$$\mathcal{T}_{ab} = -\frac{1}{8\pi} ([\mathcal{K}_{ab}] - q_{ab}[\mathcal{K}])$$

• Where  $\mathcal{K}_{ab}$  is the extrinsic curvature of  $\mathcal{H}$ ,  $\mathcal{K}$  is the mean curvature, and I use notation from (Poisson 2004) for the bracket (where A is some quantity):

$$[A] \coloneqq A(\mathcal{M}_{+})\Big|_{\mathcal{H}} - A(\mathcal{M}_{-})\Big|_{\mathcal{H}}$$

In words: evaluate the quantity A at the hypersurface
 *H* embedded in *M*<sub>+</sub>, do the same for *H* embedded in *M*<sub>-</sub>, and take the difference.

### **DEFINING ENERGY**

• If  $\chi^a$  is a timelike Killing vector on  $\mathcal{H}$ , and  $\mathcal{S}$  is a spacelike hypersurface of  $\mathcal{H}$ . If  $\mathcal{M}_{-}$  is a vacuum, then the following quantity is independent of  $\mathcal{S}$ :

$$E_{\mathcal{S}} \coloneqq -\oint_{\mathcal{S}} \mathcal{T}_{ab} \chi^{a} n^{b} \sqrt{\sigma} d^{2} y$$

- One can interpret  $E_s$  as the amount of negative mass needed to make spacetime flat outside.
- Equivalent to an intepretation by Booth & Mann; also, if
   *H* is orthogonal to constant time surfaces, this reduces to the Brown-York QLE (Booth & Mann 1999)

# SOLVING FOR ${\mathcal H}$

- Given an initial 2 surface S<sub>0</sub>, can one construct an initial value problem for *H*?
- Given a flow in *M*, defined by a timelike vector field V<sup>μ</sup>, and a 2-surface S<sub>0</sub> parametrically defined by x<sup>μ</sup><sub>0</sub>(y<sup>A</sup>), one can form *H* by evolving S<sub>0</sub> according to the flow:

$$\frac{\partial x^{\mu}}{\partial \tau} = V^{\mu}$$

- Can one, in general, define a flow in spacetime such that
   *H* has a timelike Killing vector?
- Function counting implies no; Killing's equations on *H* are too restrictive.

# **RIGID SURFACES**

One can, however, define surfaces (called *Rigid Surfaces*) that have the following properties:

$$\frac{\partial \sigma_{AB}}{\partial \tau} = 0 \quad , \qquad g_{\mu\nu} V^{\mu} V^{\nu} = -1$$

Where  $\sigma_{AB}$  is the induced metric of  $S_{\tau}$ , and  $V^{\mu}$  defines the flow  $\frac{\partial x^{\mu}}{\partial \tau} = V^{\mu}$ .

- Unit  $V^{\mu}$  ensures that  $V^{\mu}$  is a 4-velocity of some observer
- If *H* has a unit timelike Killing vector, it is a rigid surface, but the reverse is not true. Rigid surfaces with a unit timelike Killing vector will be called *Conserving Surfaces*.

#### **RIGID SURFACES: INITIAL VALUE PROBLEM**

• If  $\mathcal{H}$  is parametrically defined  $x^{\mu}(\tau, y^{A})$ , induced metric is:

$$\sigma_{AB} = g_{\mu\nu}(x^{\alpha}) \frac{\partial x^{\mu}}{\partial y^{A}} \frac{\partial x^{\nu}}{\partial y^{B}}$$

- The defining properties of rigid surfaces form a set of four PDEs for x<sup>μ</sup>(τ, y<sup>A</sup>)
- Initial Value Problem: Solve for  $x^{\mu}(\tau, y^{A})$ , given ICs:

$$x^{\mu}(\tau_0, y^A) = x_0^{\mu}(y^A)$$
,  $V_0^{\mu} = \left(\frac{\partial x^{\mu}}{\partial \tau}\right)_{\tau=\tau_0}$ 

Problem: Solutions are not unique in general (they are not unique in Minkowski space); extra conditions may be needed (zero net acceleration? Conserving Surfaces?)

# RIGIDITY



 Physically, an object is Rigid if it resists deformation.

• If  $V^{\mu}$  is orthogonal to S,  $\exists$  observers moving with rigid surface that do not see change in intrinsic geometry

 Consider a surface formed form identical masses and springs (spring const. k, equil. length l)

 For large k and small l, worldsheet will approximate a Rigid Surface.

### **RIGID SURFACES AND ENERGY**



- For Conserving surfaces,  $E_s$  makes sense as an energy, but is non-unique for non-Conserving Rigid Surfaces
- Conserving surfaces may not be embeddable in generic vacuum spacetimes
- If one can find a condition to make the IVP for Rigid Surfaces unique, Rigid Surfaces may become Conserving in different regions of spacetime.
- One can calculate energy flux through the Rigid Surface by comparing  $E_{\mathcal{S}}$ between the Conserving regions

# SOME UNRESOLVED QUESTIONS

#### The initial value problem

- How far into the future can one extend a Rigid Surface, if at all?
- What happens to Rigid Surfaces near a singularity?
- Non-Uniqueness; are there extra conditions that fix this?
  - Zero net acceleration
  - See next bullet point.
- Under what conditions can one embed a Conserving Surface (a Rigid Surface with timelike Killing vector) in spacetime?
  - $B^{\mu} \coloneqq \sigma_{\nu}^{\mu} V^{\nu} \neq 0$ . Perhaps one can place conditions on  $B^{\mu}$ ; if one has the condition that  $\sigma_{\nu}^{\mu} \mathcal{L}_{V} B^{\nu} = 0$ , Rigid Surface is Conserving.
- Would like a way to solve for constraint function:

$$f(x^{\mu})=0$$

#### REFERENCES

- 1. Poisson, E., A Relativist's Toolkit (Cambridge University Press 2004)
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- 3. Brown, J.D., York, J.W., *Quasilocal energy and conserved charges derived* from the gravitational action, Phys. Rev. D 47:1407 (1993)